

A First Embodiment of the PID Autotuning System of the Present Invention

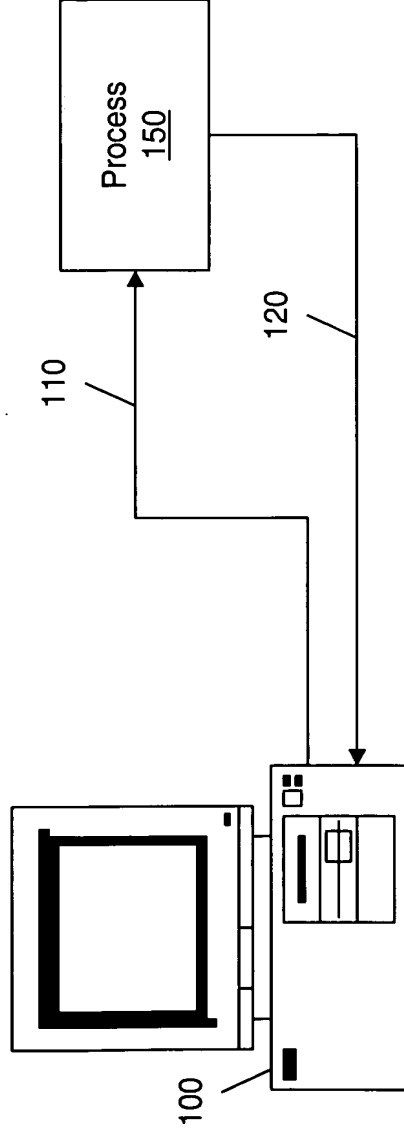


Figure 1A

A Second Embodiment of the PID Autotuning System of the Present Invention

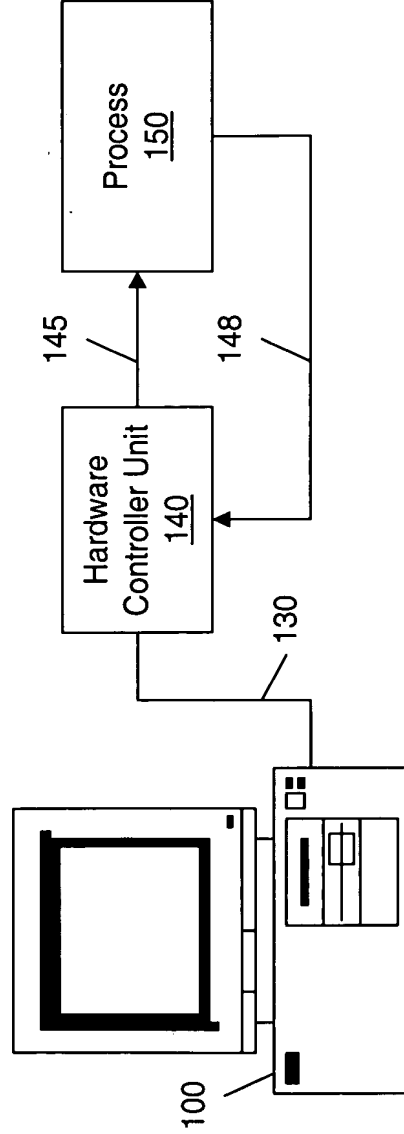


Figure 1B

000277 26897260

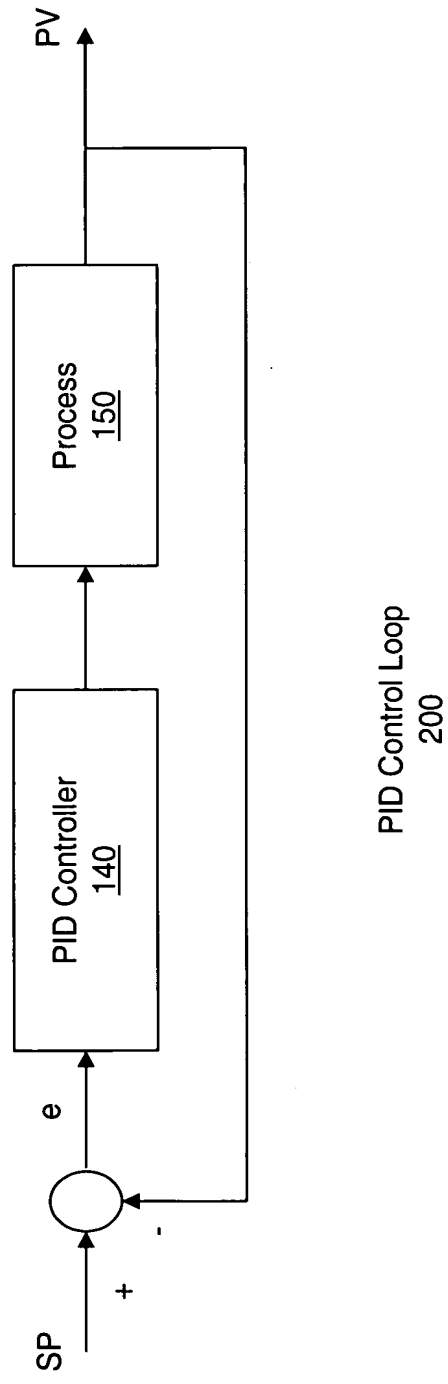


Figure 2

0971692-11000  
00021" 26891/60

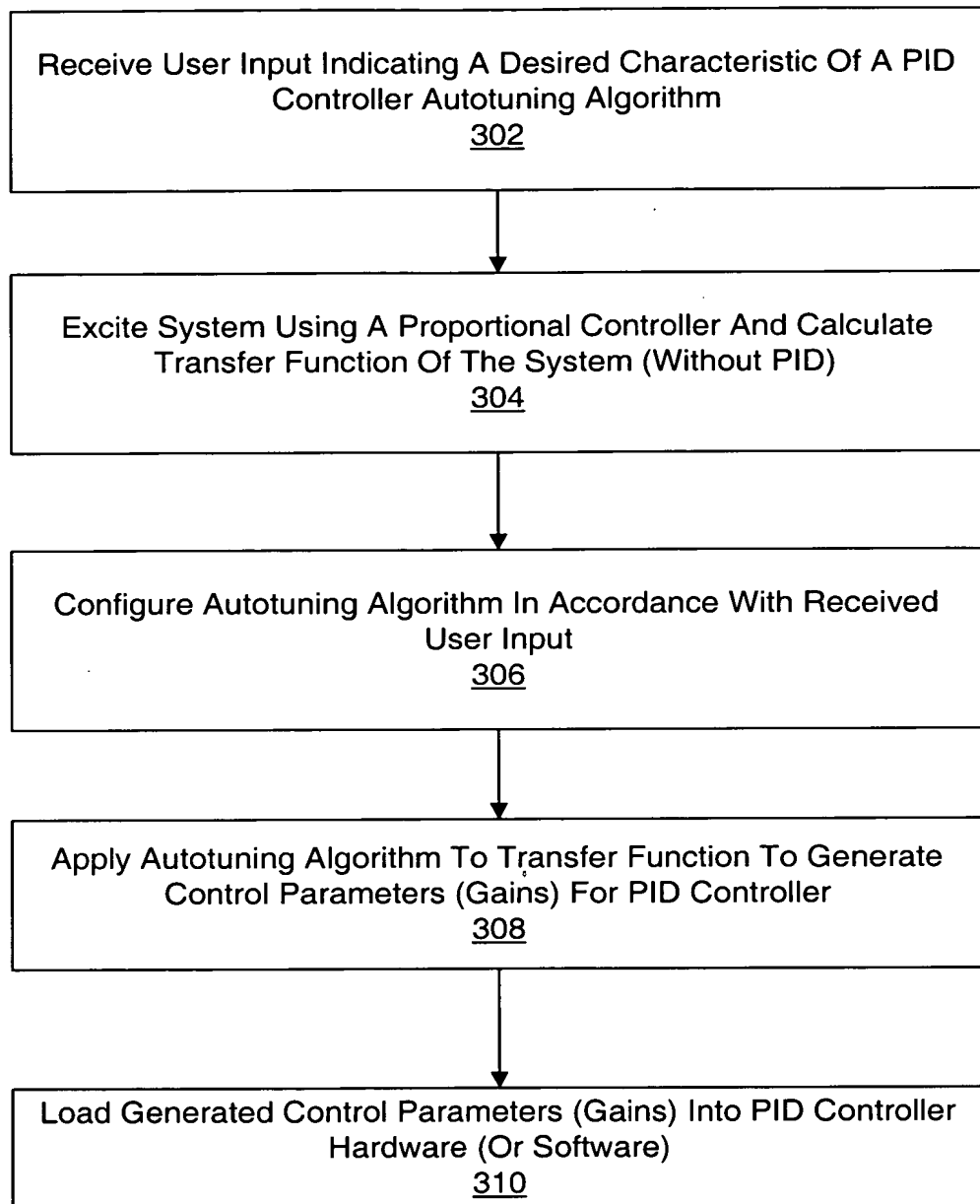


Figure 3

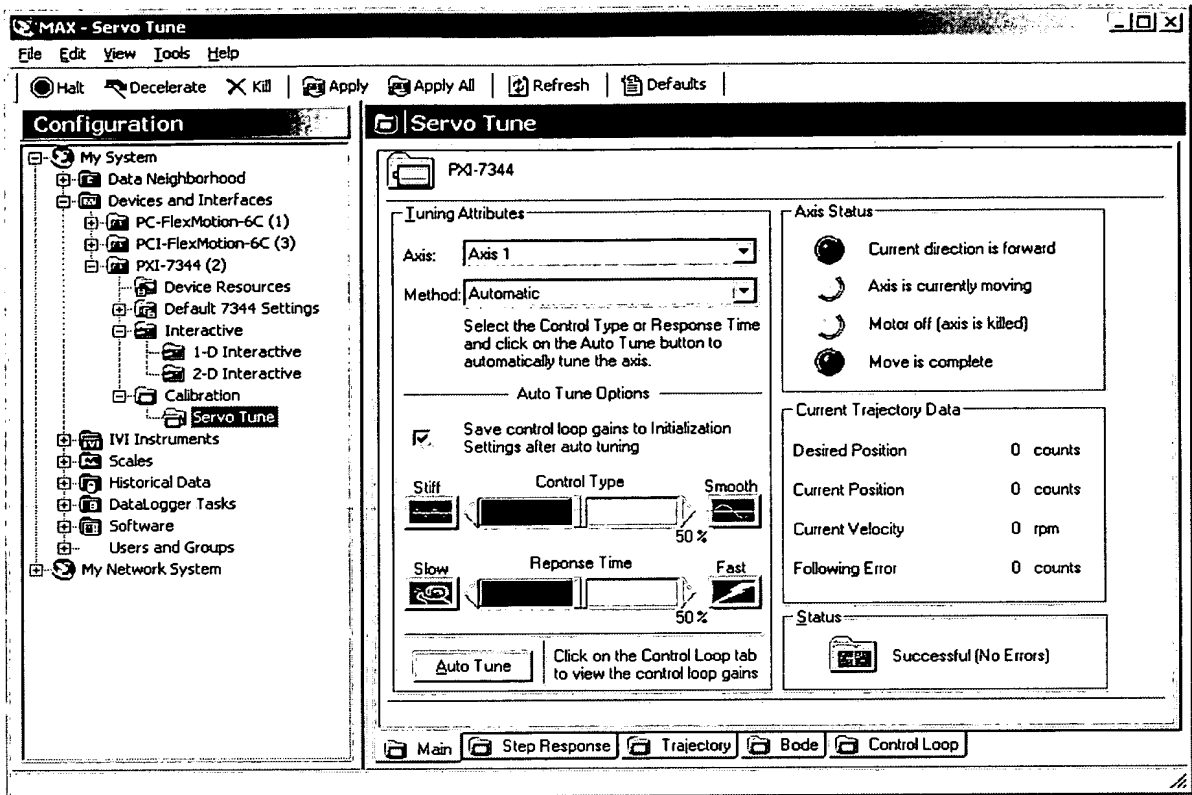


Figure 4A

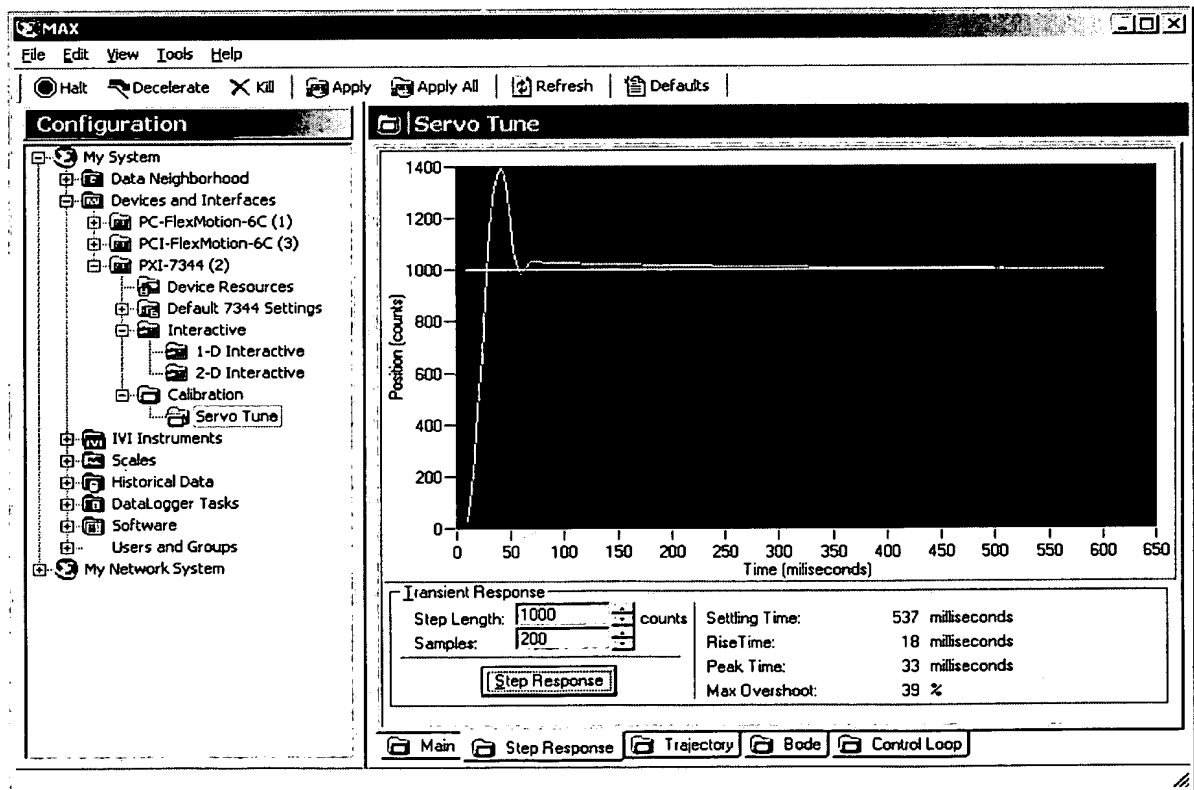


Figure 4B

09716892 " 112000

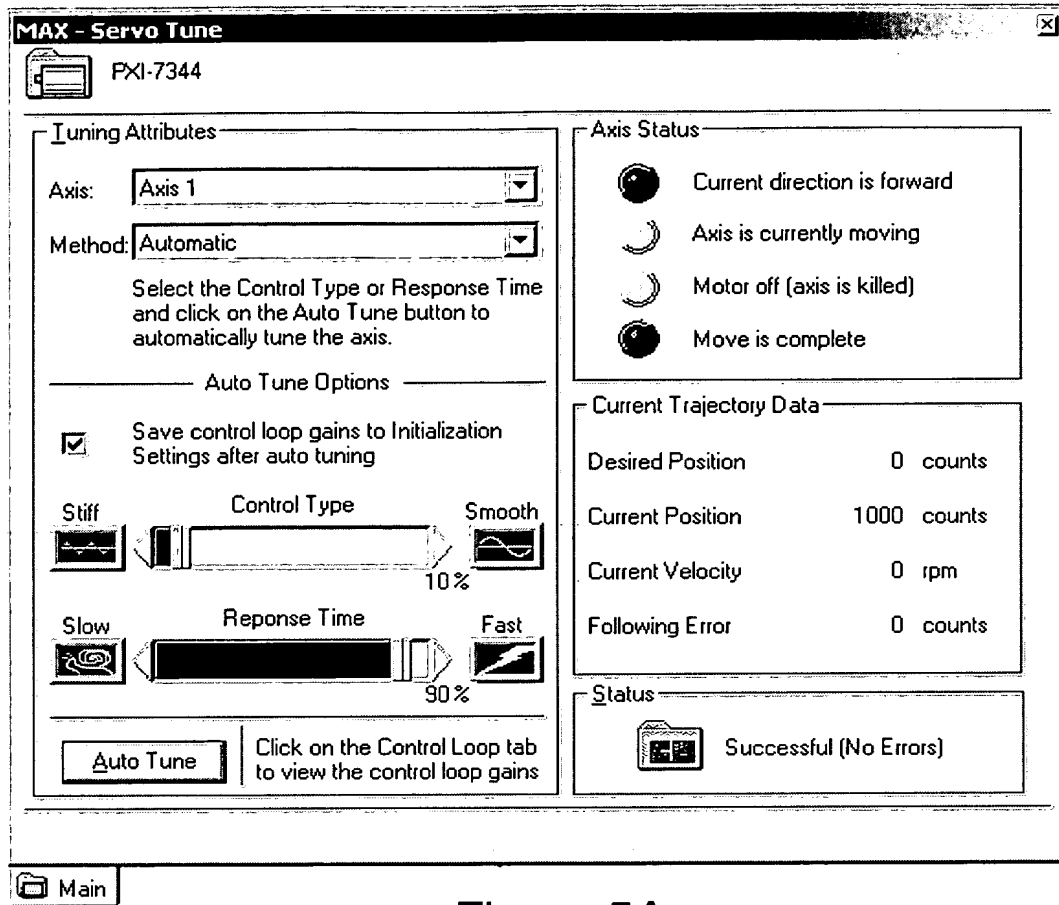


Figure 5A

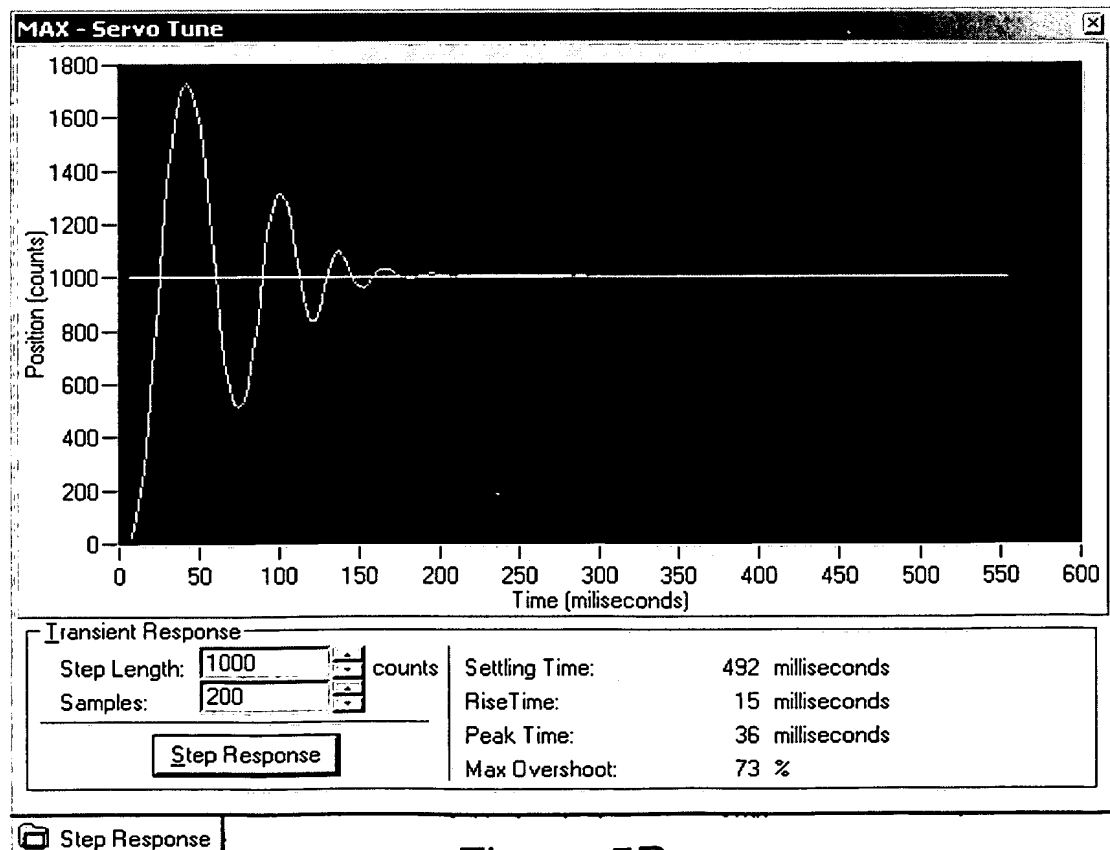


Figure 5B

000211-26891460

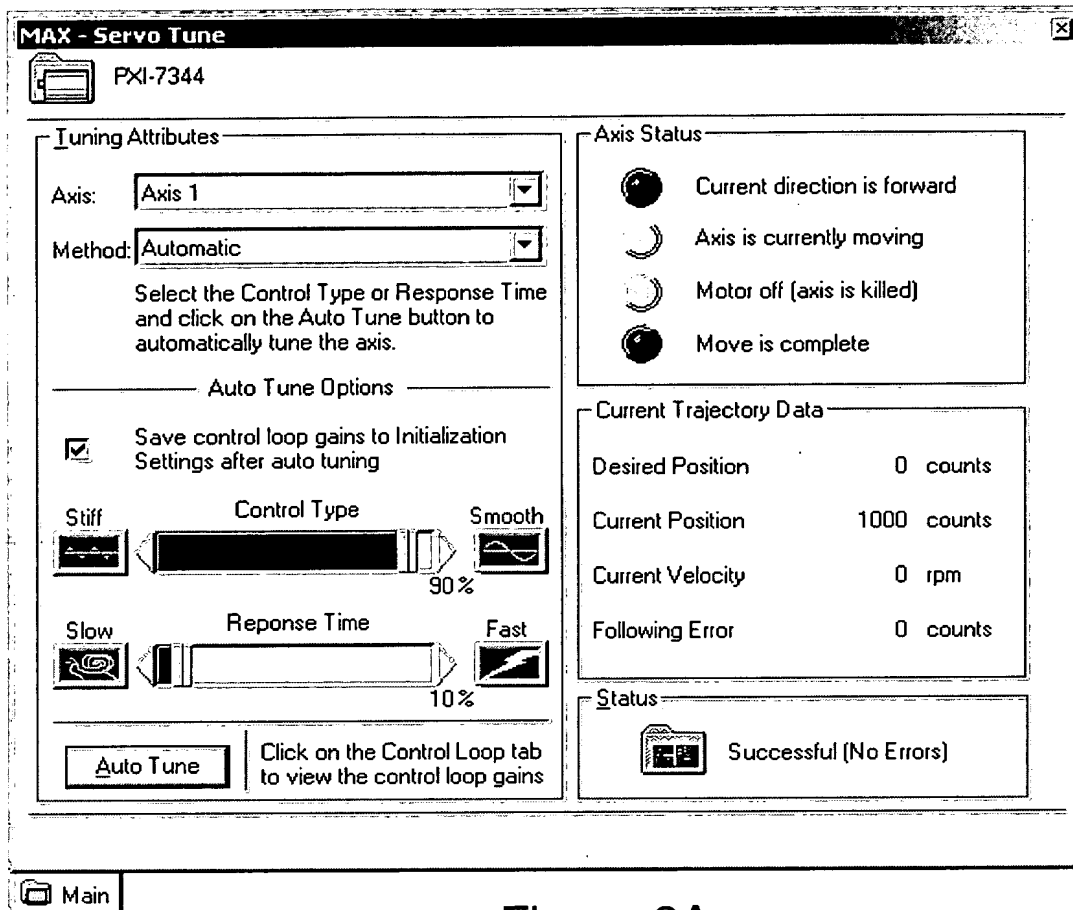


Figure 6A

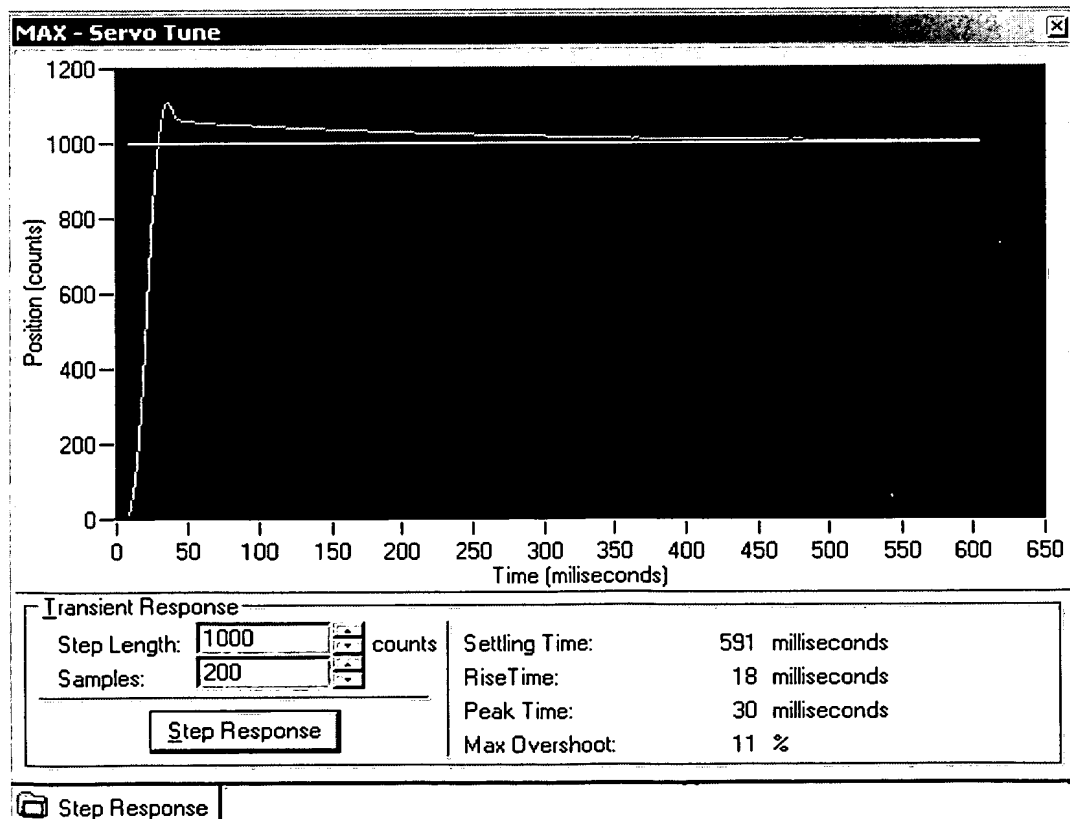


Figure 6B